JONAS SCHEER

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Tholey (Citizenship: German)

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inkedIn
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SUMMARY

Versatile Software Engineer with an extensive knowledge in various programming languages. Well versed in building products from scratch and focused on delivering projects on budget and schedule. My broad skill set reaches from building user interfaces using Flutter, over designing high performance cross-platform c++ systems as well as using Docker to manage their build & deployment cycles. R&D related tasks I prototype in Python or Matlab always having testability in mind. I organize my work using agile methods like scrum and put a high emphasis on documenting my work.

EDUCATION

MSc, Computer Science

University of Saarland & MPII Apr 2014 — Oct 2016

Thesis: A Learning Based Approach for Visual SLAM

BSc, Computer Science

University of Saarland & DFKI

Oct 2008 - Mar 2014

Thesis: Toolkit for Augmenting Arbitrary Surfaces using Mobile Projection and Depth Camera

SKILLS

- Software Engineering
- Computer Vision
- Computer Graphics

C++ (c++20 / TMP)
 advanced 7 years
 CMake
 intermediate 4 years

2 vears

Java / Kotlin

intermediate 3 years

Flutter

basics

- Android
- OpenCV
- OpenGLPython
- Matlab
- Unit Tests / OOP
- Docker / Kubernetes
- ❖ Git
- CI/CD
- ❖ Unix / Shell
- Linux / Win / OSX

LANGUAGES

German: Native English: Fluent Chinese: Basics

PROFESSIONAL EXPERIENCE

Senior Software Engineer

Luxemburg - Mar 2023 - Present

- Lead dev. Computer Vision SDK (Cross Platform Android & C++ & AOSP)
- Supervise Development e.g. Enforce Reviews, Core Guidelines, Style Guide
- Setup CI Pipeline & Test Framework (Bitbucket, Catch2)
 Evaluate Image Quality of Cameras
- Manage Scrum backlog

Software Engineer

Tholey (Germany) - Mar 2022 - Mar 2023

- · Published Flutter Plugin: flutter_opengl_view
- Porting libgphoto2 to CMake
- Build SLAM based Capturing App from scratch (see YouTube)

Self Employed

ARRI

Intel

ARSpectra

Development Engineer

Munich (Germany) - Sep 2017 - Feb 2022

- Imaging Algorithms & Pipeline (Matlab)
- SLAM & Photogrammetry (C++)
- Color Calibration Application (Java, C++)
- Camera Calibration (C++, Matlab)
- Various Research Collaborations: Fraunhofer IIS & HHI, FAU & TUM

Research Assistant

Saarbrücken (Germany) — Jun 2016 — Jun 2017

- Developing RGB+D Streaming Application for Virtual Reality (C++, C#, Unity)
- Working on Multi-View Reconstruction using Intel RealSense cameras

Intel Visual Computing Institute

Working Student

Saarbrücken (Germany) — Jun 2014 — Dec 2015

- Multi-Camera Calibration (Python, C++)
- Feature Detection & Matching
- Training Random Forest classifier for SLAM/SfM

PUBLICATIONS

GCPR - 2016

J. Scheer, M. Fritz, O. Grau — Learning to Select Long Track Features for Structure-From-Motion & Visual SLAM

3DTV-Con - 2017

J. Scheer, C. F. Quemada, O. Grau — A Client-Server Architecture for Real-time View-Dependent Streaming of Free-Viewpoint Video